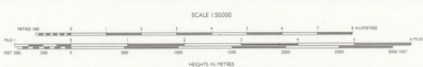


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Users requiring corrections or additions to this map are
requested to complete and send to the Ethiopian
Mapping Agency, P.O. Box 997, Addis Ababa, Ethiopia.
The map will be updated.



INDEX TO ADJOINING SHEETS

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SYMBOLS		HEIGHTS IN METERS		ABBREVIATIONS	
[Symbol]	Mountain	[Symbol]	1000	[Symbol]	1. Airfield
[Symbol]	Pass	[Symbol]	2000	[Symbol]	2. Railway
[Symbol]	Peak	[Symbol]	3000	[Symbol]	3. Road
[Symbol]	Peak with snow	[Symbol]	4000	[Symbol]	4. River
[Symbol]	Peak with snow and ice	[Symbol]	5000	[Symbol]	5. Lake
[Symbol]	Peak with snow and ice and forest	[Symbol]	6000	[Symbol]	6. Dam
[Symbol]	Peak with snow and ice and forest and forest	[Symbol]	7000	[Symbol]	7. Canal
[Symbol]	Peak with snow and ice and forest and forest and forest	[Symbol]	8000	[Symbol]	8. Well
[Symbol]	Peak with snow and ice and forest and forest and forest and forest	[Symbol]	9000	[Symbol]	9. Spring
[Symbol]	Peak with snow and ice and forest and forest and forest and forest and forest	[Symbol]	10000	[Symbol]	10. Pond

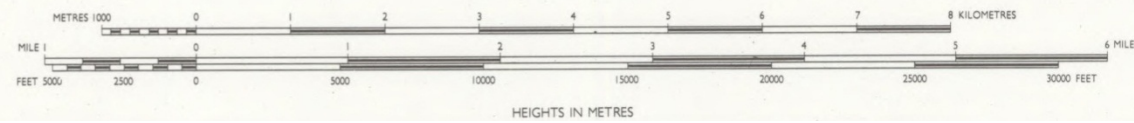
CONTOUR

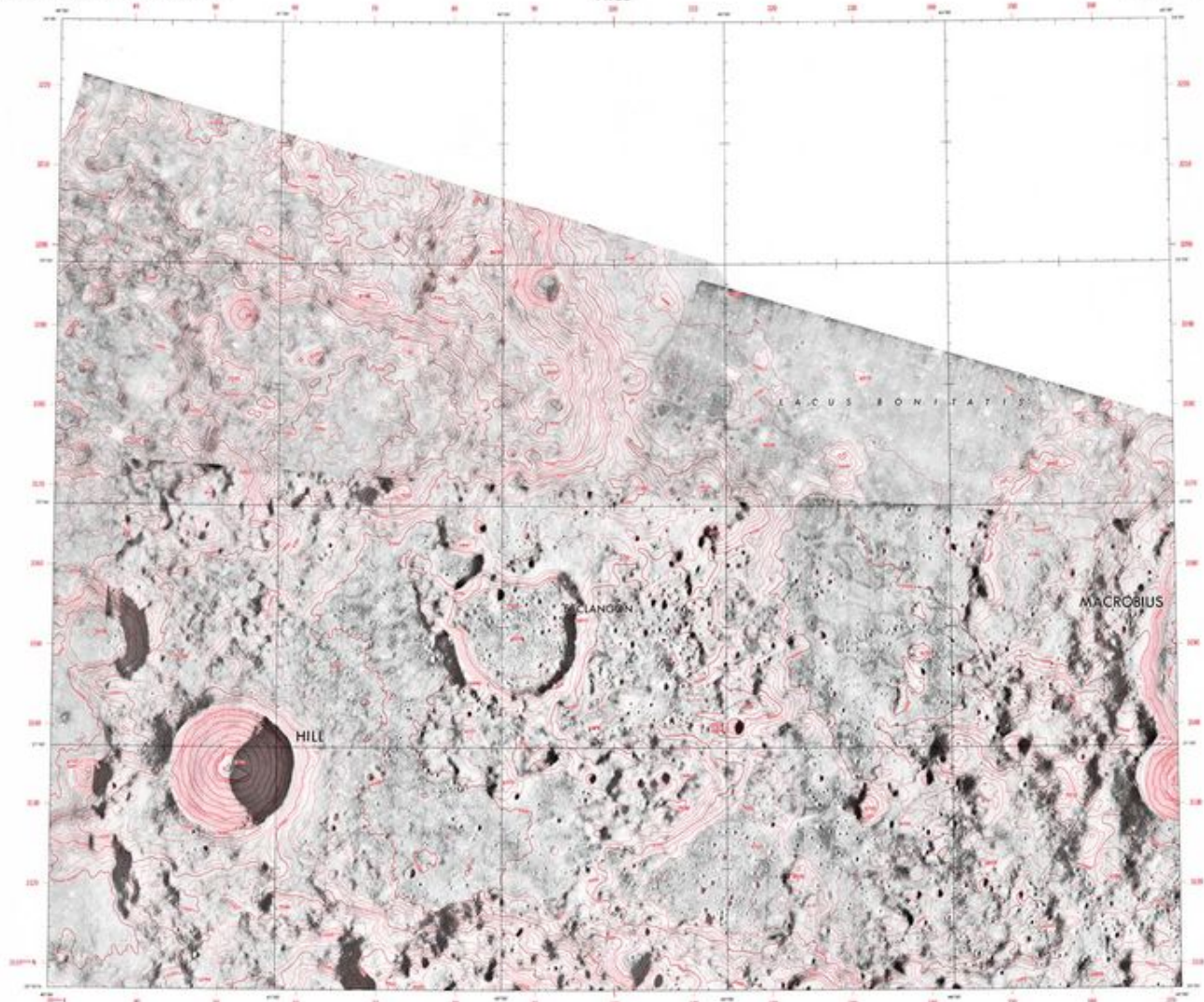
100	1000	10000
200	2000	20000
300	3000	30000
400	4000	40000
500	5000	50000
600	6000	60000
700	7000	70000
800	8000	80000
900	9000	90000
1000	10000	100000



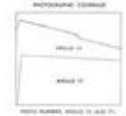
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SCALE 1:50,000





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 NATIONAL AERONAUTICS AND SPACE ADMINISTRATION, U.S.
 GOVERNMENT PRINTING OFFICE: 1974



TRANSVERSE MERCATOR PROJECTION

THIS MAP IS A TRANSVERSE MERCATOR PROJECTION OF THE LUNAR SURFACE. THE PROJECTION IS BASED ON THE WGS 1984 EARTH REFERENCE FRAME. THE PROJECTION IS BASED ON THE WGS 1984 EARTH REFERENCE FRAME. THE PROJECTION IS BASED ON THE WGS 1984 EARTH REFERENCE FRAME.

UTM ZONE	18Q
EARTH REFERENCE FRAME	WGS 1984
PROJECTION	Transverse Mercator
SCALE FACTOR AT CENTRE	0.9996076327
FALSE EASTING (M)	500000
FALSE NORTING (M)	10000000
SEMI-MAJOR AXIS (M)	6378137
SEMI-MINOR AXIS (M)	6356752.3142
ECCENTRICITY	0.081818541137
ECCENTRICITY SQUARED	0.00669438456
INVERSE FLATTENING	298.257222101
LONGITUDE OF CENTRE (DEGREES)	105.0
NORTHING OF CENTRE (M)	10000000
EASTING OF CENTRE (M)	500000

TOPOGRAPHIC DATA

LOCATION MAP TO SHEET

CONTINUOUS SCALE

STOCK NO. LTO43C1(1) (250)

photogrammetry

photogrammetry

(T. Schenk 2005)

Photogrammetry is the science of obtaining reliable information about the properties of surfaces and objects without physical contact with the objects, and of measuring and interpreting this information.

The name "photogrammetry" is derived from the three Greek words *phos* or *phot* which means light, *gramma* which means letter or something drawn, and *metrein*, the noun of measure.

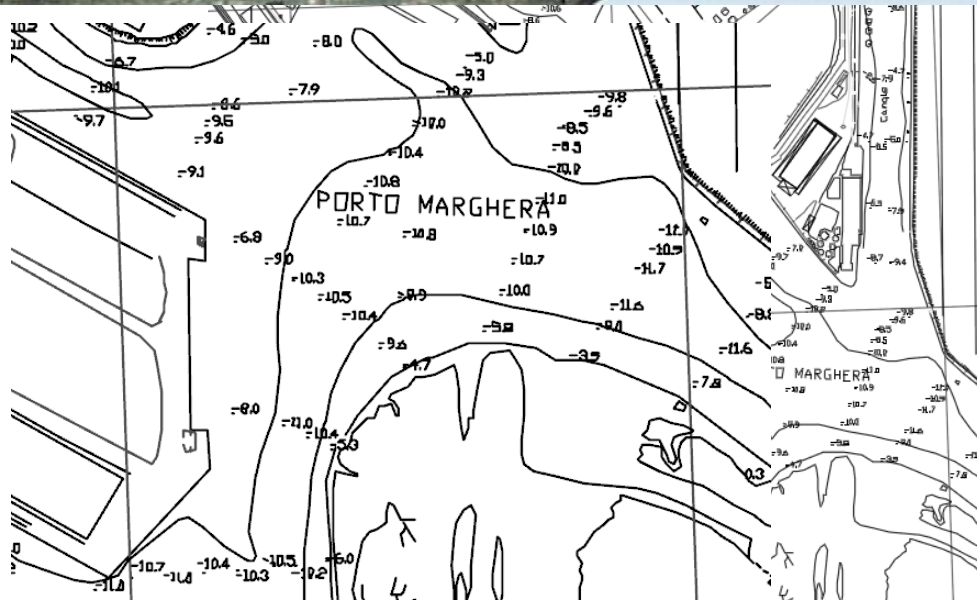
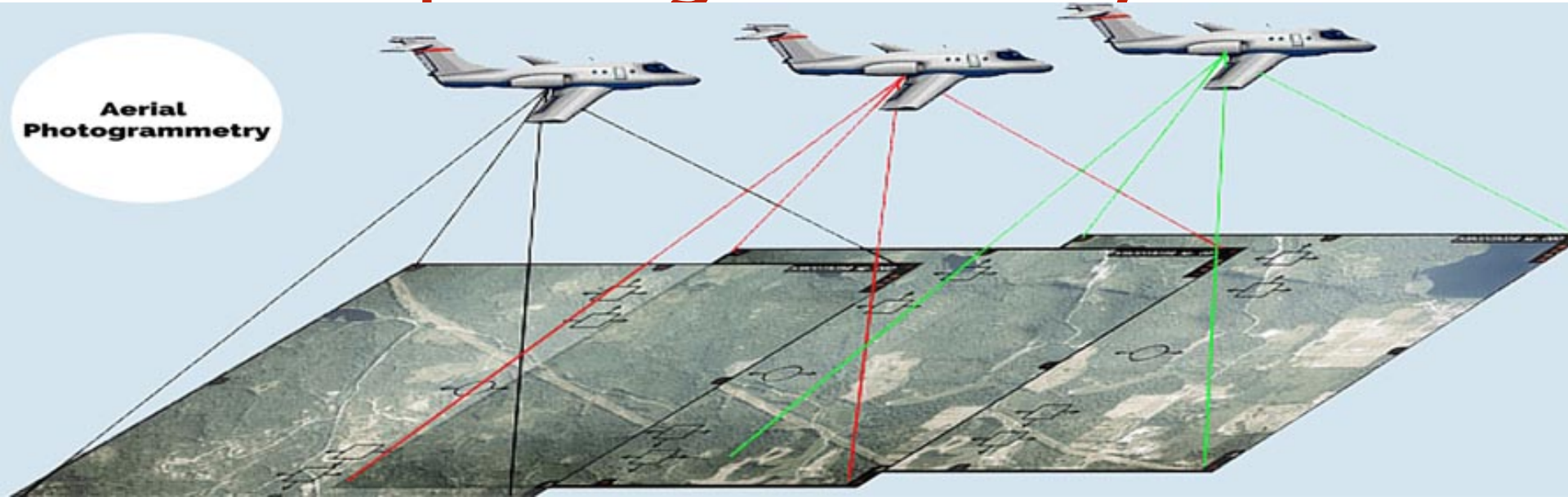


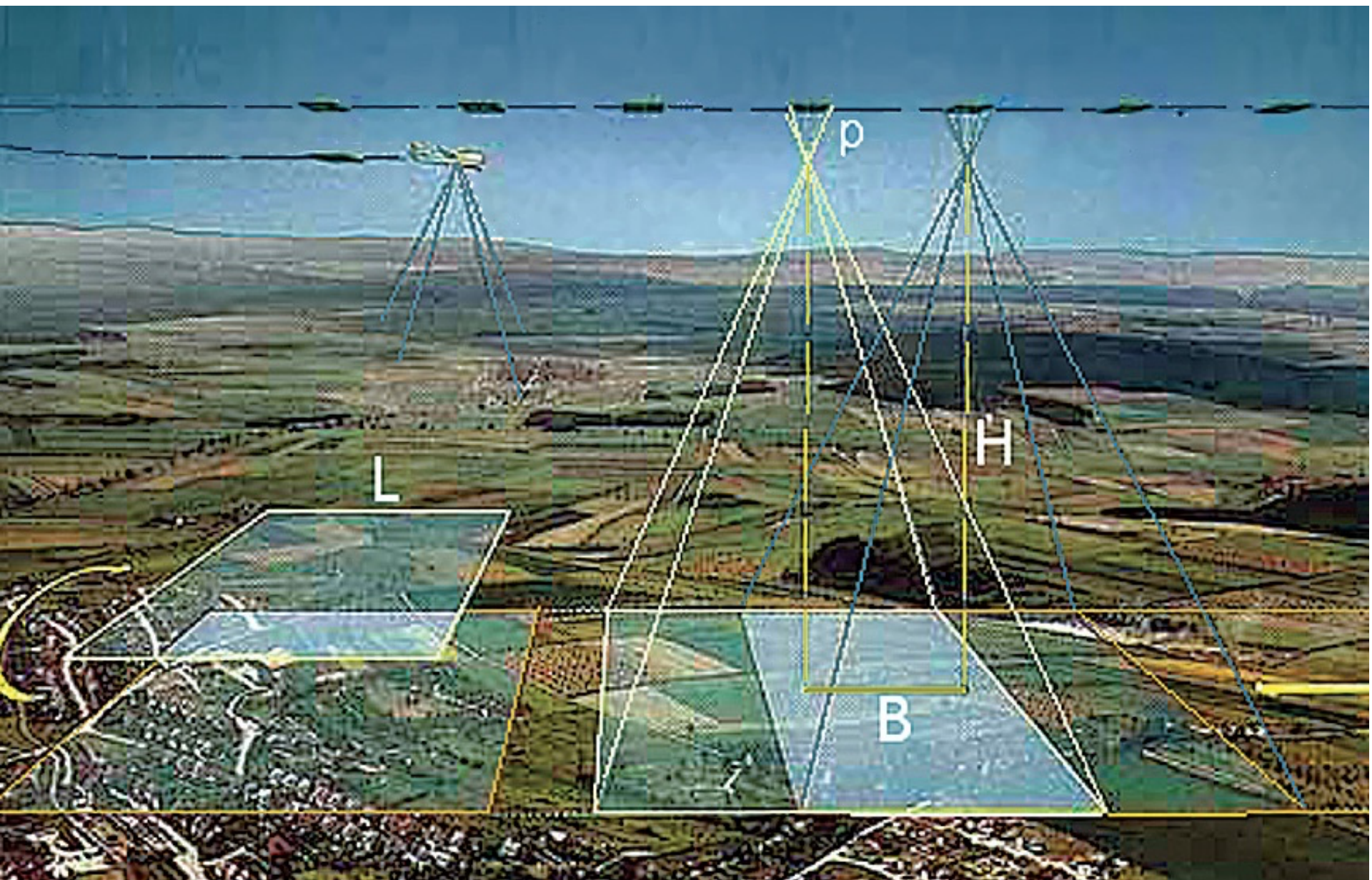
The first known aerial photograph was obtained by Gaspard Felix Tournachon (Nadar) from a tethered balloon 1,700-ft. above Paris, France in 1858.

This is an oblique photograph obtained from the Hippodrome Balloon using a multiband camera.

photogrammetry

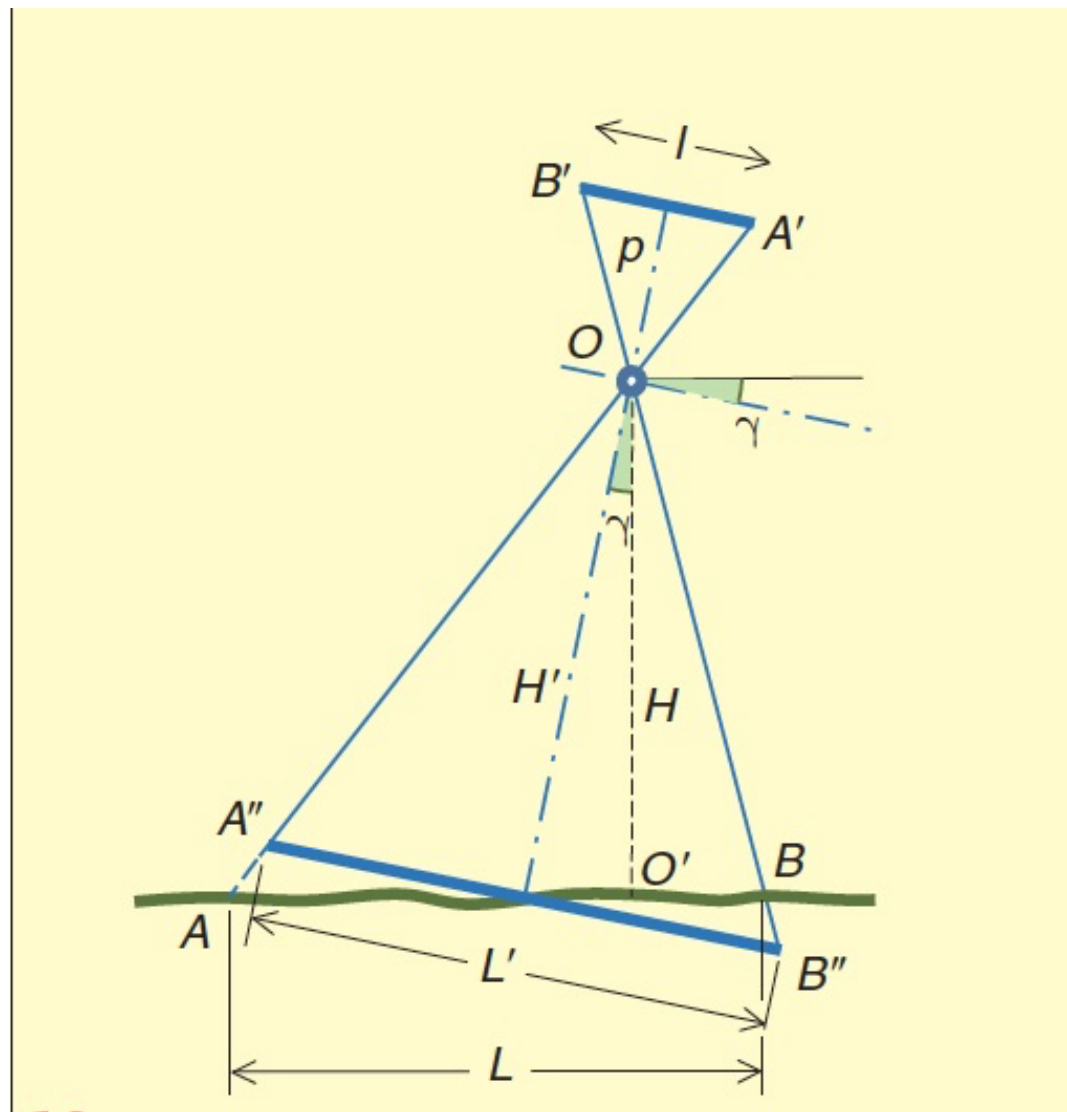
**Aerial
Photogrammetry**

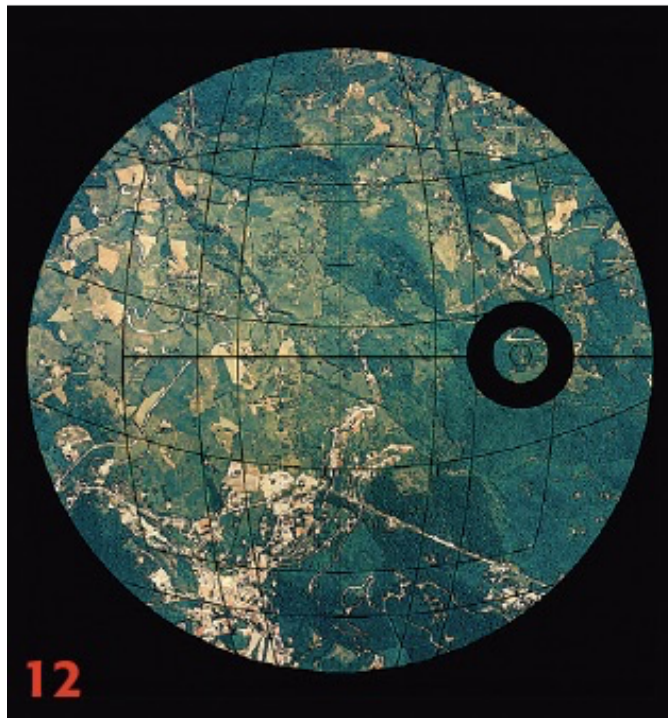












FIUME SECCHIA



1

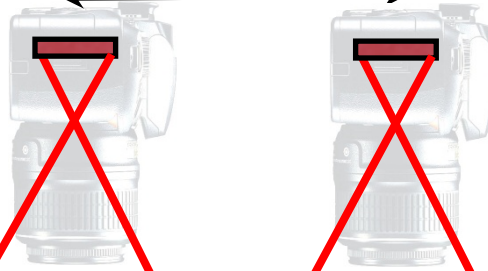


5139

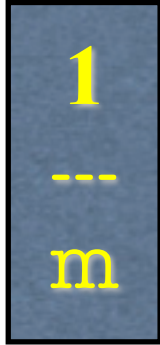
5139



b = base di presa



$$\frac{f}{D} = \frac{l}{L} = \frac{1}{m}$$



scala media



$L_{st} = \text{zona stereoscopica} = 60\% L$







UAGI 3043 15274

10-11-81

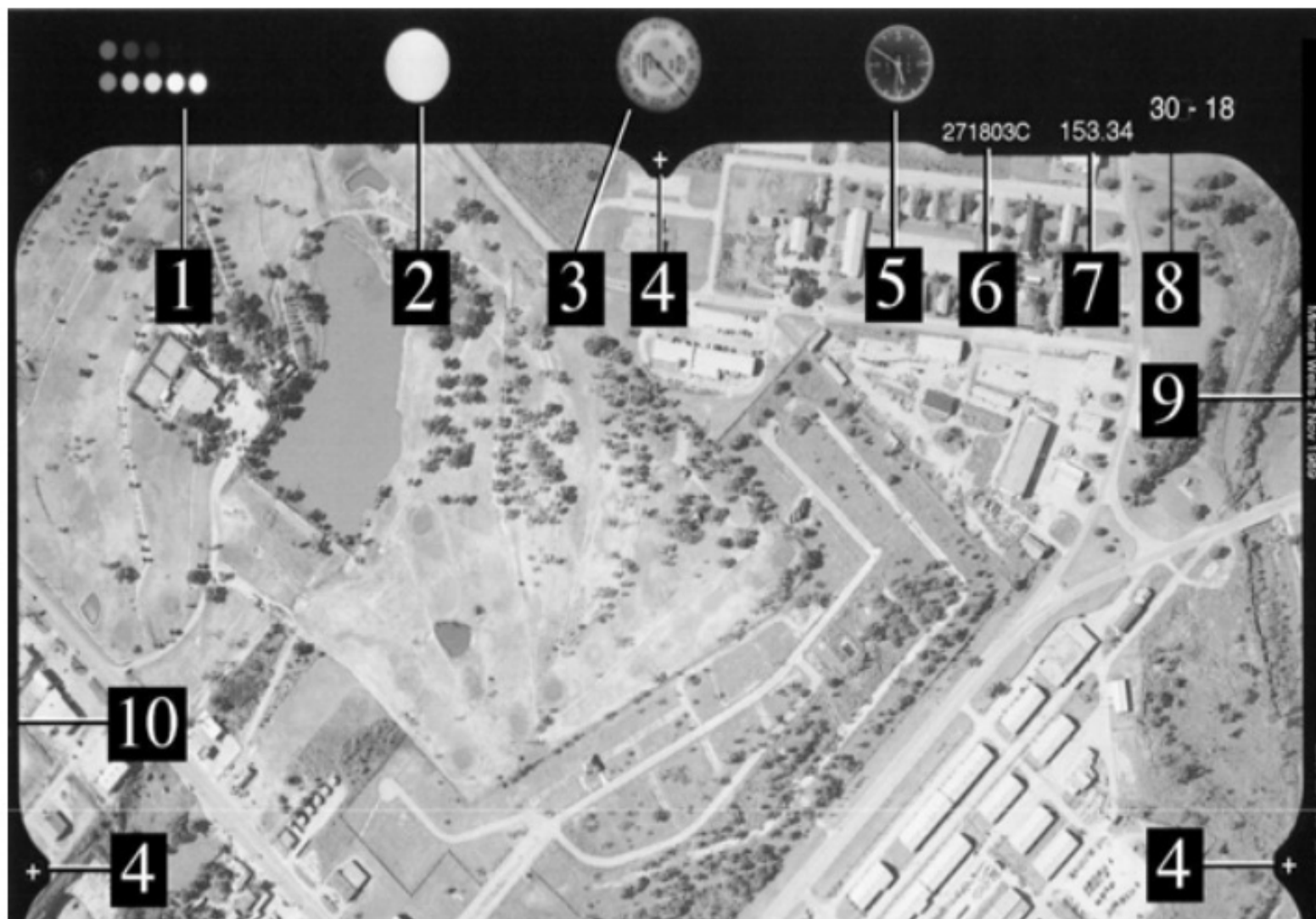
NO . 0781

988FD7

08-20-98

NOS

Annotation on the Perimeter of An Aerial Photograph



1. Grayscale
2. Notepad
3. Altimeter

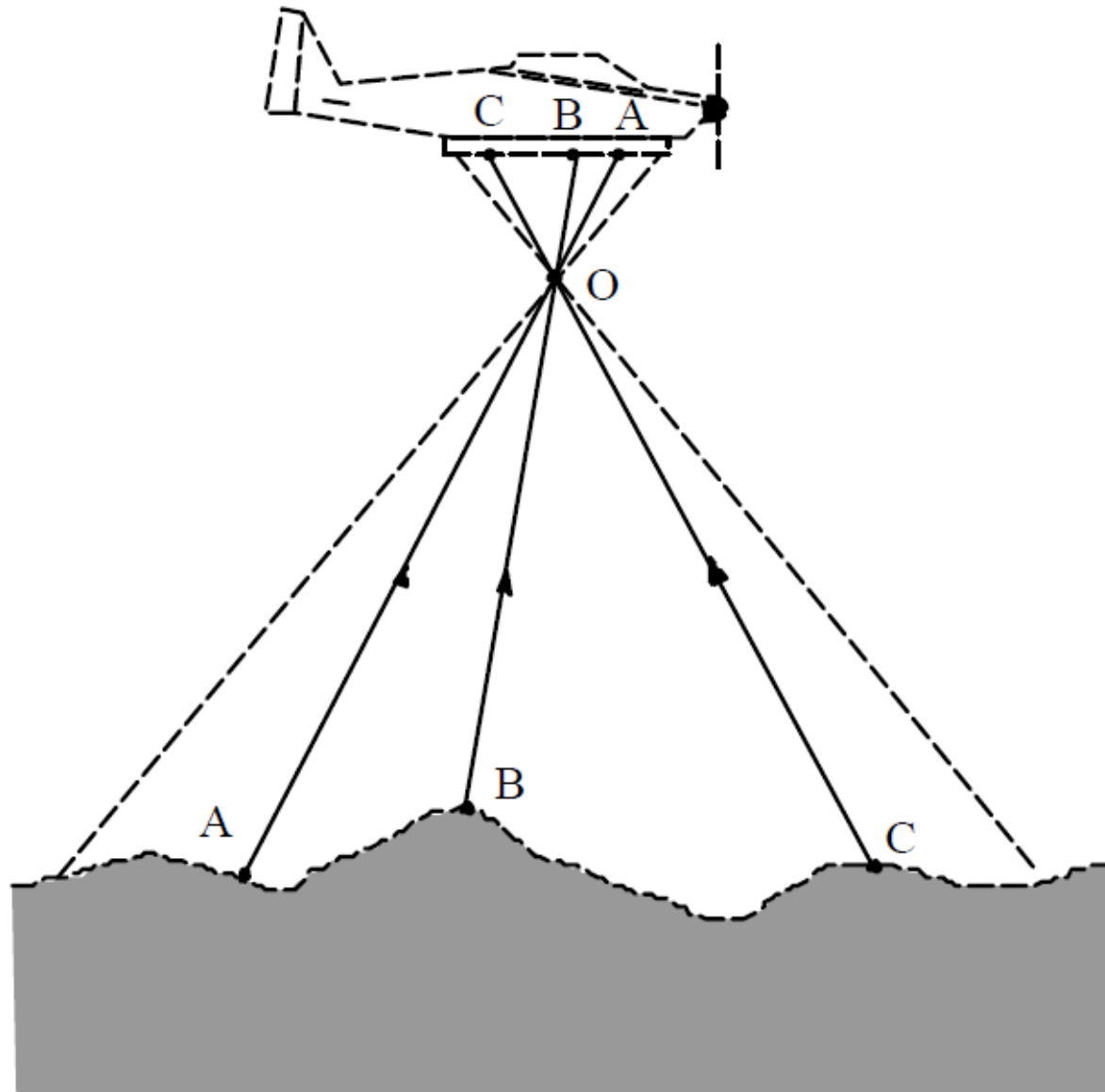
4. Fiducial marks
5. Clock
6. Lens cone Serial #

7. Focal length **10. Navigation Data**
8. Frame Number
9. Mission Name & Date

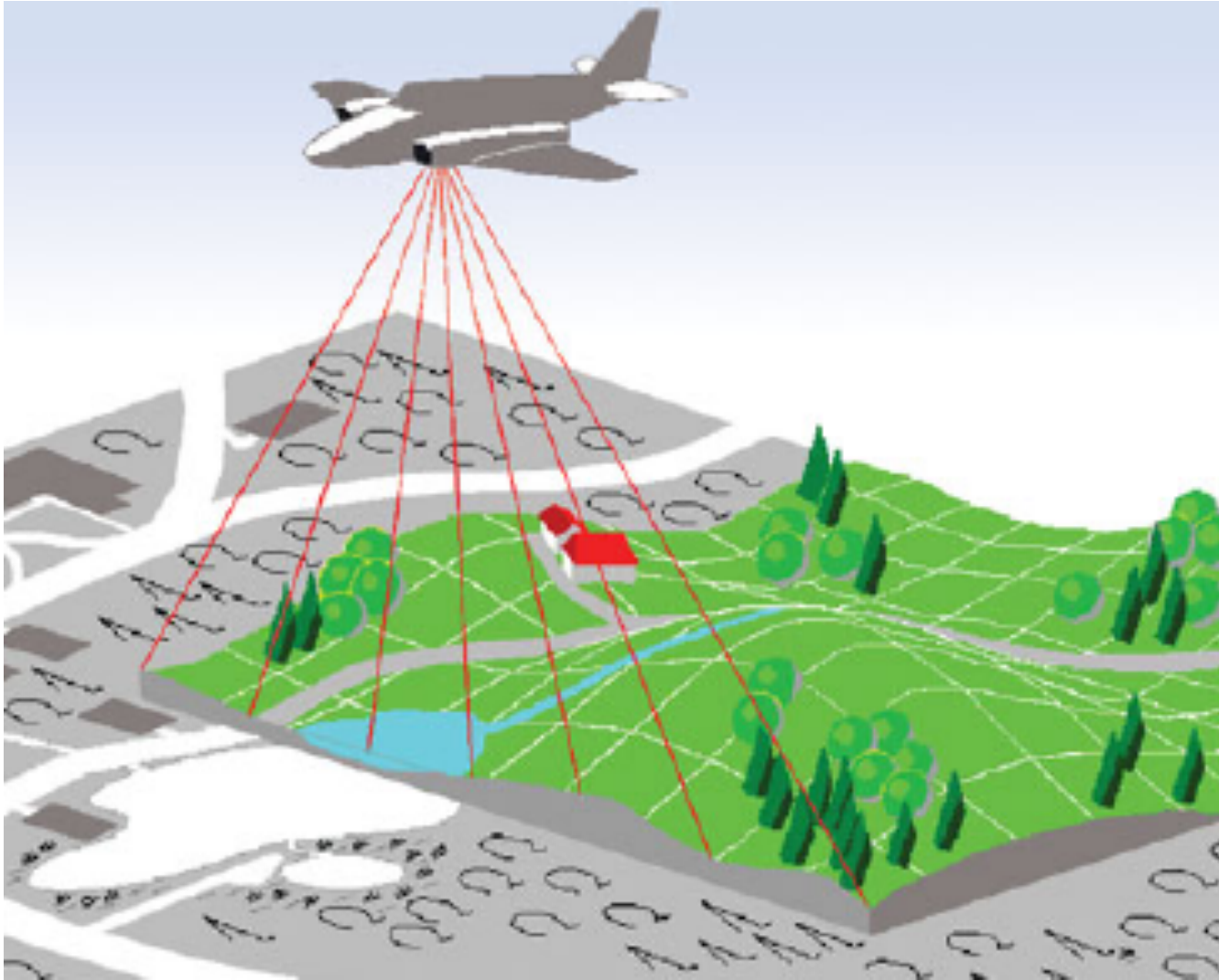
Aerial
photography
provides a
picture of the
land.

Geometrically
defines a **central
projection**,
because
the rays that
produce the
images on the
photograph from
the ground all
pass through the
same point which
is the **center of
objective O**

Aerial photo



not only photo with Aerial Survey



Airborne LIDAR Survey

LiDAR: What and Why?

- LiDAR stands for **Light Detection and Ranging**
- LiDAR is not only replacing conventional sensors, but also creating new methods with unique properties that could not be achieved before

LiDAR: How?

- Each time the laser is pulsed:
 - Laser generates an optical pulse
 - Pulse is reflected off an object and returns
 - to the system receiver
 - High-speed counter measures the time of flight from the start pulse to the return pulse
 - Time measurement is converted to a distance (the distance to the target and the
 - position of the airplane is then used to determine
 - the elevation and location)
 - Multiple returns can be measured for each pulse
- Up to 200,000+ pulses/second
- Everything that can be seen from the aircraft
 - is measured





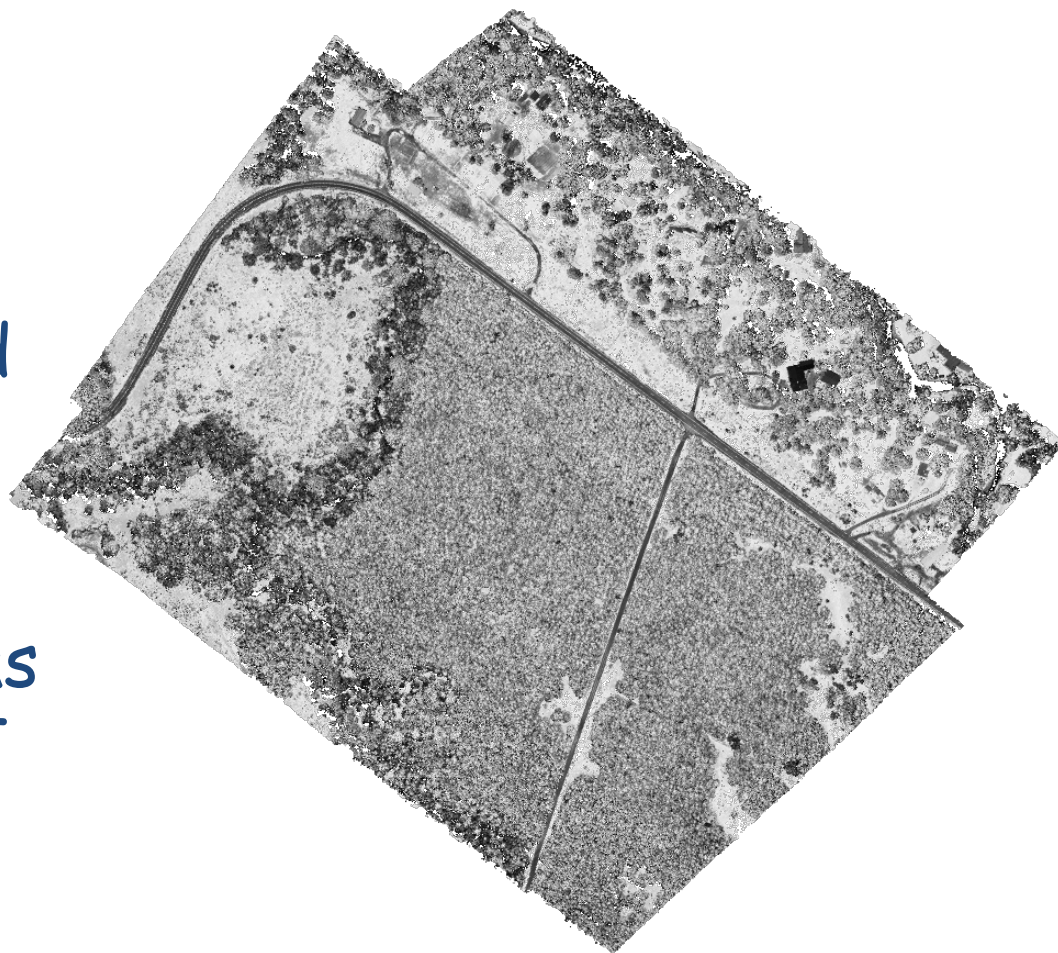
Traditional Photogrammetry vs. LiDAR

LiDAR	Photogrammetric
Day or night data acquisition	Day time collection only
Direct acquisition of 3D collection	Complicated and sometimes unreliable procedures
Vertical accuracy is better than planimetric*	Planimetric accuracy is better than vertical*
Point cloud difficult to derive semantic information; however, <u>intensity</u> values can be used to produce a visually rich image like product (example of an intensity image)	Rich in semantic information

***Complementary characteristics suggest integration**

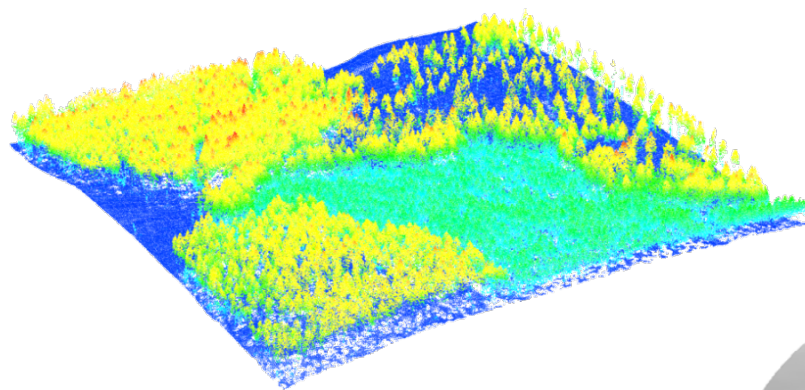
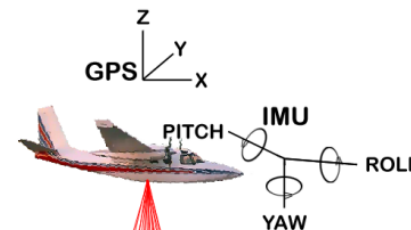
Intensity Image

- Commonly unused by-product of a LiDAR acquisition and is the intensity of object that the laser pulse is striking. This is an uncalibrated 8-bit (0-255) image that is ortho-rectified as therefore can be used as an orthophoto
- Not typically used in quantitative analysis as image gains always set to 'adaptive gain' setting when images are acquired

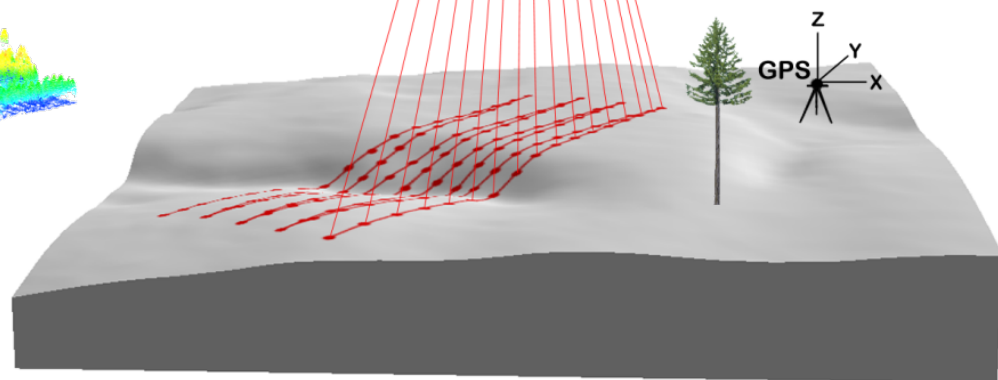


Aerial LiDAR System Components

- Aircraft
- Scanning laser emitter-receiver unit
- Differentially-corrected GPS
- Inertial measurement unit (IMU)
- Computer



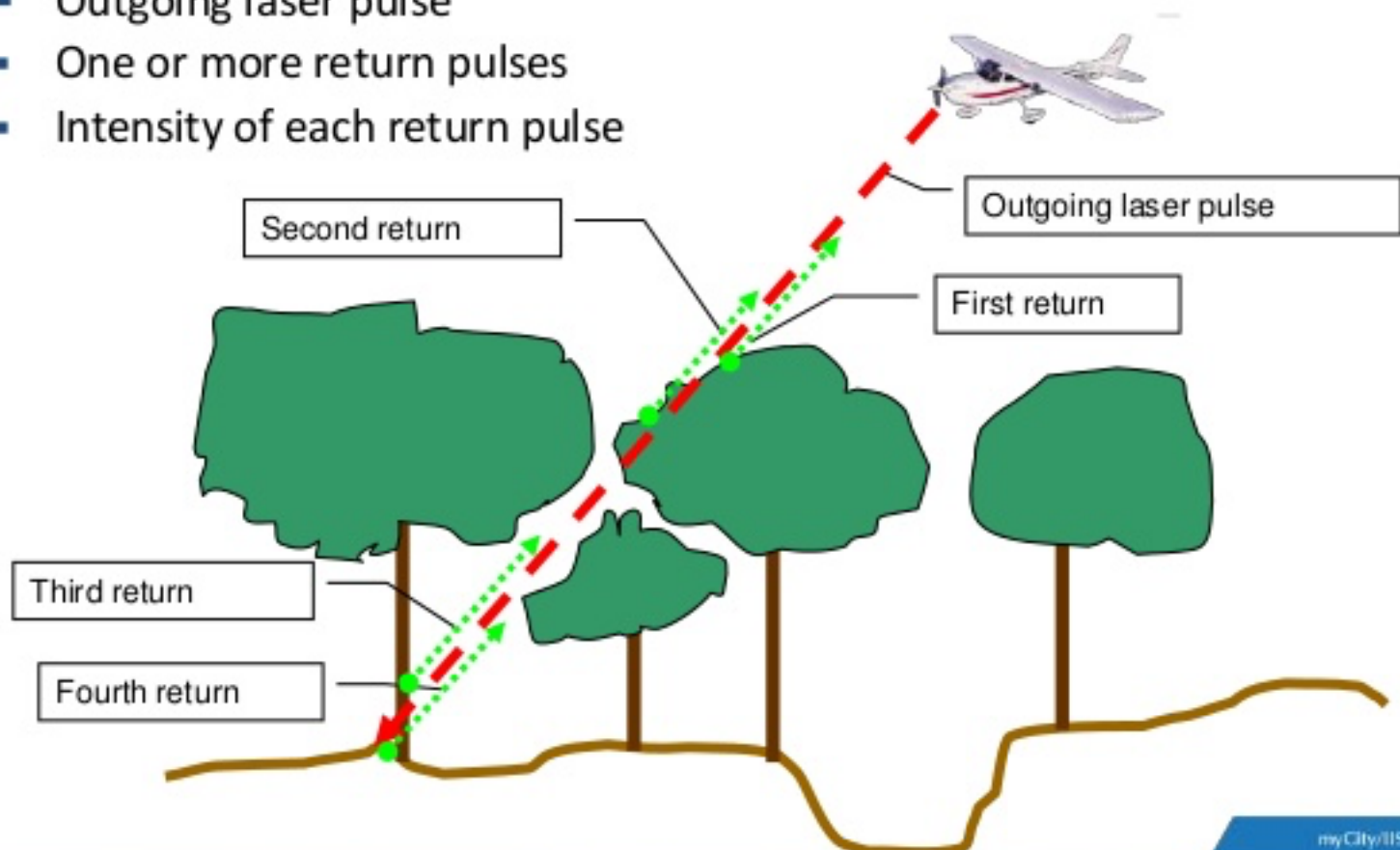
LiDAR point data colored by height



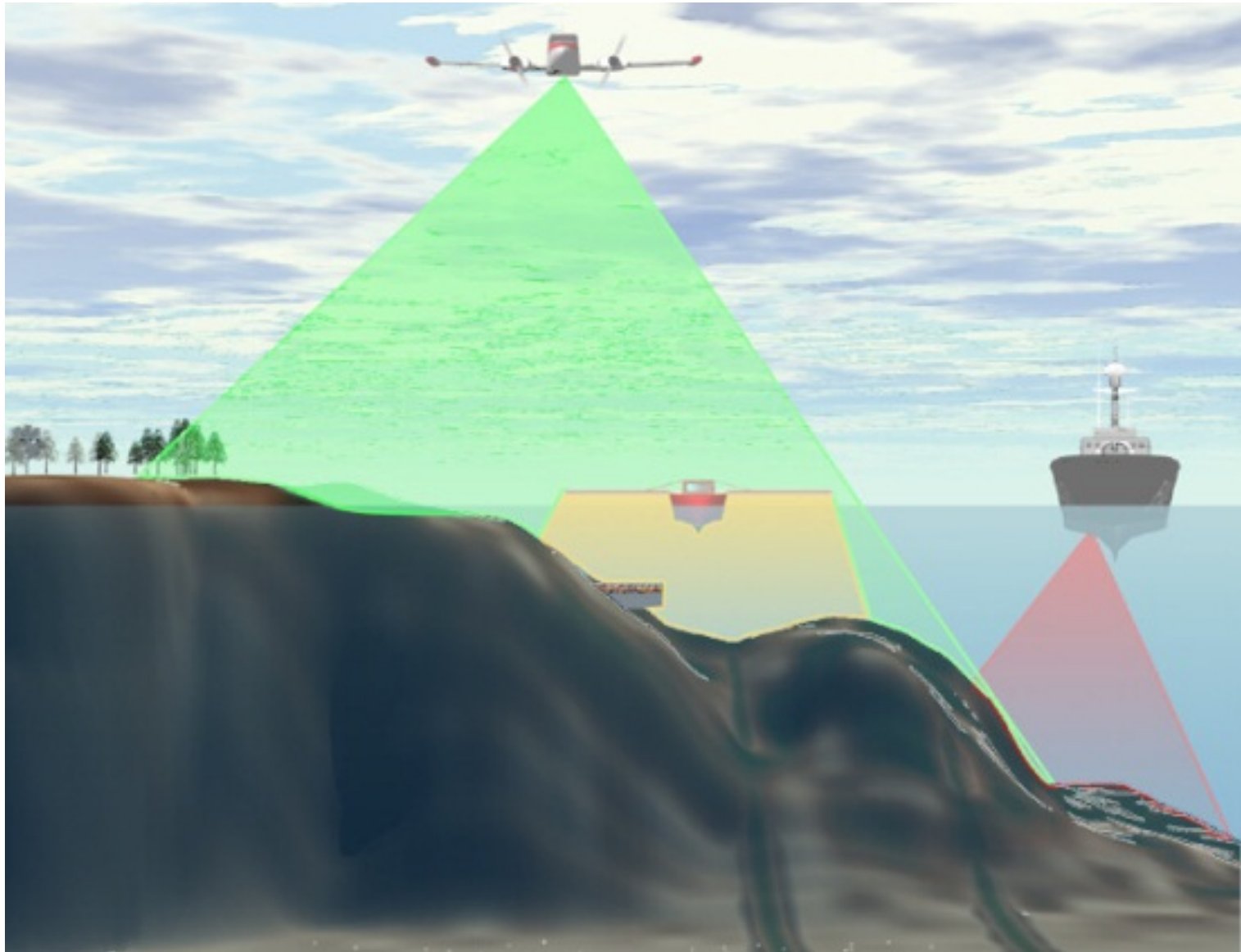
LIght Detection And Ranging

LiDAR Principles

- Outgoing laser pulse
- One or more return pulses
- Intensity of each return pulse



Special Services involving Aerial Survey

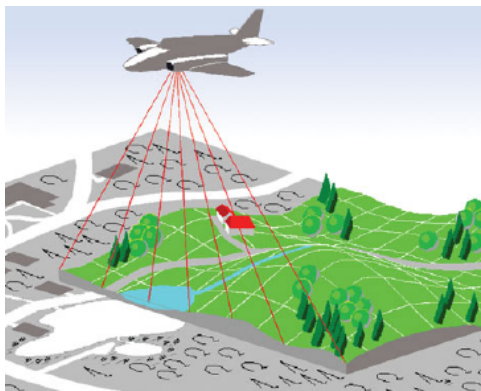


Airborne LIDAR Hydrography (SHOALS)

Special Services (LIDAR Survey)

Multi sensor system operated on-board an airplane or helicopter. Scanning the survey area strip by strip the position and altitude measurements are also recorded.

LIDAR and the Optical Scanner.



Virtual Reality

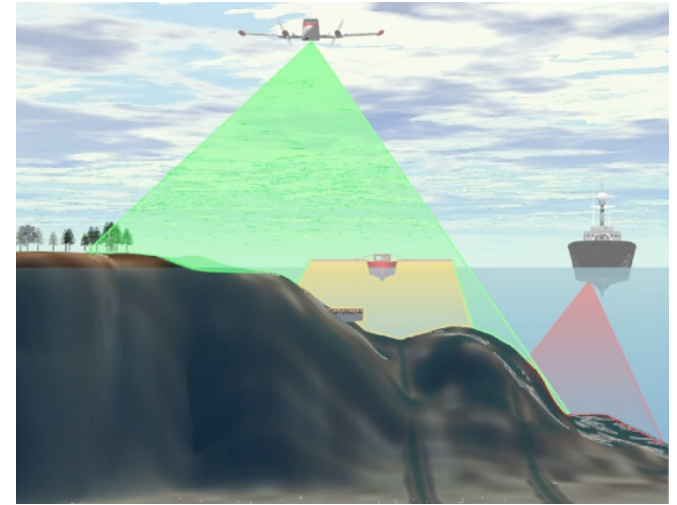


Applications:

- [3D City Models and Urban Planning](#)
- [Monitoring and Protection of Coastal Zones](#)
- [Corridor Mapping, Pipelines and Transmission Lines](#)
- Forest Inventory and Precision Management
- [Surface Mining and Deposits](#)
- Flood Protection and Hydraulic Simulations
- [Power lines](#)

Special Services (LIDAR Bathymetry)

Airborne laser bathymeter system can survey over large areas, far exceeding the capabilities and efficiency of traditional survey methods. LIDAR has a unique capability to map shallow waters, shoreline and topography simultaneously, integrating land and water measurements in the same data set. This technology not only speed up the total survey mission and project turn around time, but also allow surveys over sensitive environmental coastal zones or inland water ways.



The products may include:

- ✧ Digital Terrain Models (DTM)
- ✧ Digital Surface Model (DSM)
- ✧ Ortho-photos and mosaics
- ✧ Topographic maps
- ✧ Other LIDAR data